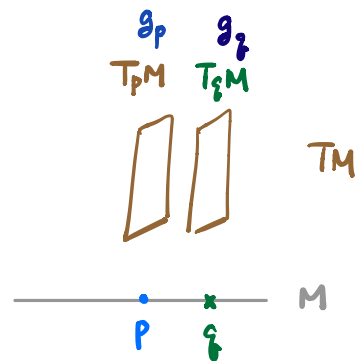


[Announcement: HW3 due today, HW4 posted.]

Recall: (M^m, g) Riemannian manifold

is • a C^∞ mfd M^m

• \exists fiber (pos. def.) metric $g^{\langle \cdot, \cdot \rangle}$ on $TM \rightarrow M$.



Fundamental Thm. of Riem. Geometry

Given a Riem. mfd (M^m, g) , $\exists!$ connection D on TM s.t.

- (1) $Dg \equiv 0$ metric compatible
 - (2) $T \equiv 0$ torsion free
- } Riemannian / Levi-Civita connection

Proof: (Constructive proof)

GOAL: Derive an explicit formula of D using ONLY (1), (2).

For $X, Y, Z \in \mathfrak{X}(M)$.

$$X \langle Y, Z \rangle \stackrel{(1)}{=} \langle D_X Y, Z \rangle + \langle Y, D_X Z \rangle$$

$$+ Y \langle Z, X \rangle \stackrel{(1)}{=} \langle D_Y Z, X \rangle + \langle Z, D_Y X \rangle$$

$$- Z \langle X, Y \rangle \stackrel{(1)}{=} \langle D_Z X, Y \rangle + \langle X, D_Z Y \rangle$$

$$\text{R.H.S.} = \langle D_X Y + D_Y X, Z \rangle + \langle D_X Z - D_Z X, Y \rangle + \langle D_Y Z - D_Z Y, X \rangle$$

$$\stackrel{(2)}{=} \langle 2D_X Y - [X, Y], Z \rangle + \langle [X, Z], Y \rangle + \langle [Y, Z], X \rangle$$

Rearrange the terms,

$$2 \langle D_X Y, Z \rangle = \langle [X, Y], Z \rangle - \langle [X, Z], Y \rangle - \langle [Y, Z], X \rangle - Z \langle X, Y \rangle + Y \langle X, Z \rangle + X \langle Y, Z \rangle$$

defines $D_X Y$

only involves $\langle \cdot, \cdot \rangle = g$ and $[\cdot, \cdot]$

locally in coordinates :

$$\Gamma_{ij}^k = \frac{1}{2} g^{ke} (g_{ej,i} + g_{ie,j} - g_{ij,e})$$

Koszul's formula

Remark: $T_j^k \approx F(g, \partial g)$.

By general connection theory,

D Levi-Civita connection on TM \rightsquigarrow Riemann curvature $\text{Riem} = R$

$\forall X, Y \in \mathfrak{X}(M)$, $R(X, Y) : TM \rightarrow TM$, i.e. $R \in \mathcal{T}(\wedge^2 T^*M \otimes \text{End}(TM))$

locally $R = \{\Omega_j^i\}$, Ω_j^i : local 2-forms on M

Suppose: e_1, \dots, e_m basis for TM

$\theta^1, \dots, \theta^m$ dual basis for T^*M

We can write $\Omega_j^i = \frac{1}{2} \sum_{k, l} R_{jkl}^i \theta^k \wedge \theta^l$ where $R_{jkl}^i = -R_{jlk}^i$

lower its index: $\Omega_{ij} := \sum_p g_{ip} \Omega_j^p = \frac{1}{2} \sum_{k, l} R_{ijkl} \theta^k \wedge \theta^l$.

Symmetries of R_{ijkl} :

✓ (1) $R_{ijkl} = -R_{ijlk} = -R_{jikl}$

✓ (2) $R_{ijkl} + R_{iklj} + R_{iljk} = 0$ (1st Bianchi identity)

✓ (3) $R_{ijkl} = R_{klij}$

Pf: (1) 1st "=" by defⁿ, 2nd "=" $\because \Omega_{ji} = -\Omega_{ij}$ for metric compatible D.

(2) Locally in basis: $\underline{e} = (e_1, \dots, e_m)$; $\underline{\theta} = \begin{pmatrix} \theta^1 \\ \vdots \\ \theta^m \end{pmatrix}$.

$$D \underline{e} = \underline{e} \omega \quad \Rightarrow \quad d \underline{\theta} = -\omega \wedge \underline{\theta}$$

(HW)

$$\begin{aligned} \text{So, } 0 &= d^2 \underline{\theta} = -d\omega \wedge \underline{\theta} + \omega \wedge d \underline{\theta} \\ &= -d\omega \wedge \underline{\theta} + \omega \wedge (-\omega \wedge \underline{\theta}) \\ &= -(\underbrace{d\omega + \omega \wedge \omega}_{=: \Omega}) \wedge \underline{\theta} \end{aligned}$$

Thus, we obtained $\Omega \wedge \underline{\theta} = 0$

More explicitly, $\frac{1}{2} \sum_{j,k,l} R^i{}_{jkl} \theta^k \wedge \theta^l \wedge \theta^j = 0$

Look at the components,

$$\Rightarrow (R^i{}_{jkl} + R^i{}_{kjl} + R^i{}_{ljk}) - (R^i{}_{kjl} + R^i{}_{jlk} + R^i{}_{lkj}) = 0$$

lower index $\Rightarrow (R_{ijkl} + R_{iklj} + R_{iljk}) - (R_{ikjl} + R_{ijlk} + R_{ilkj}) = 0$

$$\Rightarrow 2(R_{ijkl} + R_{iklj} + R_{iljk}) = 0$$

(1) + (2) \Rightarrow (3):

$$R_{ijkl} + R_{iklj} + R_{iljk} \stackrel{(2)}{=} 0$$

$$-) R_{jikl} + R_{jkli} + R_{jlki} \stackrel{(2)}{=} 0$$

$$2 R_{ijkl} + R_{iklj} + R_{iljk} + R_{jkli} + R_{jlki} = 0$$

$\underbrace{\hspace{10em}}$
invariant under
 $(i,j) \leftrightarrow (k,l)$

Remarks: $R_{ijkl} = R(e_i, e_j, e_k, e_l)$ $R = (0,4)$ -tensor

$$R(x, Y) e_j = \Omega^i{}_j(x, Y) e_i \Rightarrow \Omega_{ij}(x, Y) = \langle R(x, Y) e_j, e_i \rangle$$

i.e. $R(x, Y, Z, W) = -\langle R(x, Y) Z, W \rangle$

In local coord.

$$R^i{}_{jkl} = \Gamma^i{}_{lj,k} - \Gamma^i{}_{kj,l} + \Gamma^p{}_{lj} \Gamma^i{}_{kp} - \Gamma^p{}_{kj} \Gamma^i{}_{lp} \quad (\text{Ex:})$$

Remark: $g = (g_{ij}) \rightsquigarrow D = \{\Gamma^k{}_{ij}\} = F(g, \partial g)$

$$\rightsquigarrow R = [R_{ijkl}] = \tilde{F}(g, \partial g, \partial^2 g)$$

One consequence of the symmetries of R_{ijkl}

At $p \in M$, $\mathcal{R}_p : \Lambda^2 T_p M \times \Lambda^2 T_p M \rightarrow \mathbb{R}$

st. $\mathcal{R}_p(e_i \wedge e_j, e_k \wedge e_l) := R_{ijkl}$

Curvature operator
acting on $\Lambda^2 T_p M$
(or $\Lambda^2 T^* M$)

(1) \Rightarrow well-defined

(3) \Rightarrow symmetric

Defⁿ: $F: (M^m, g) \rightarrow (N^m, h)$ is an **isometry**

if $F: M \rightarrow N$ is diffeomorphism & $F^*h = g$.

Remark: Riem. is a "geometric invariant" (indep. of coord.)

$$F: (M, g) \rightarrow (N, h) \Rightarrow F^*(\text{Riem}(h)) = \text{Riem}(g)$$

isometry
ie $F^*h = g$

E.g.) "Locally" isometric manifolds have the "same" Riem. curvature

Q: How much does Riem. curvature determine the metric?

"A": In general, it's not fully. But sometimes true.

Thm: (M^m, g) $\text{Riem}(g) \equiv 0 \iff (M^m, g)$ is locally isometric to (\mathbb{R}^m, δ)

Standard
Euclidean
metric

Proof: (\Leftarrow) trivial.

(\Rightarrow) Suppose (M^m, g) with $\text{Riem}(g) \equiv 0$, i.e. D is flat.

Fix $p \in M$, and e_1, \dots, e_m O.N.B. of T_pM .

D flat $\Rightarrow \exists$ parallel extension of e_1, \dots, e_m (ie. $D e_i \equiv 0$)
in a nbd. of p in M near p

Let $g_{ij} := \langle e_i, e_j \rangle \equiv \langle e_i, e_j \rangle(p) = \delta_{ij}$

↑
parallel

GOAL: Show \exists local coord. x^1, \dots, x^m of M st $e_i = \frac{\partial}{\partial x^i}$.

Consider dual basis of 1-forms, $\theta^1, \dots, \theta^m$ of e_1, \dots, e_m

Recall: $d\theta^i = -\omega^i_j \wedge \theta^j \stackrel{D \text{ flat}}{=} 0$, ie. $d\theta^i \equiv 0$

By "Poincaré lemma", $\theta^i = dx^i$ for some fcn x^i near p

So, $\langle \theta^i, \theta^j \rangle \equiv \delta_{ij} \Rightarrow F: (M, g) \rightarrow (\mathbb{R}^m, \delta)$ is local isometry.
 $\mathfrak{p} \mapsto (x^1(\mathfrak{p}), \dots, x^m(\mathfrak{p}))$



Remark: Globally may have topology, e.g. flat torus $T^n = \mathbb{R}^n / \Delta$

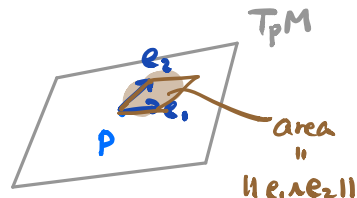
but the thm. is true passing to the universal cover \tilde{M}

Note: Riem. curvature Riem of (M^m, g) is the higher dimensional analogue to the notion of Gauss curvature for surfaces (in \mathbb{R}^3).

• When $m=2$ (surface case),

$$\mathcal{R}_p : \wedge^2 T_p M \times \wedge^2 T_p M \rightarrow \mathbb{R} \quad \text{say } \wedge^2 T_p M = \text{span}\{e_1 \wedge e_2\}$$

$$K_p = \mathcal{R}_p \left(\frac{e_1 \wedge e_2}{\|e_1 \wedge e_2\|}, \frac{e_1 \wedge e_2}{\|e_1 \wedge e_2\|} \right) = \frac{R_{1212}}{\|e_1 \wedge e_2\|^2}$$



Gauss curvature \rightsquigarrow at p

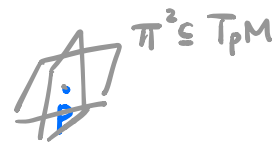
In general, we have

Def: Let $\pi^2 \subseteq T_p M$ be a 2-dim. subspace w/ basis $\{v, w\}$.

$$K_p(\pi) := \frac{\mathcal{R}(v \wedge w, v \wedge w)}{\|v \wedge w\|^2} \quad \text{section curvature of } \pi \text{ at } p$$

Note: $K_p(\pi)$ is indep. of choice of basis $\{v, w\}$ for π .

$$K_p : \underbrace{\text{Gr}(2, T_p M)}_{\{\pi \subseteq T_p M : \pi \text{ 2-dim subspace}\}} \longrightarrow \mathbb{R}$$



locally: e_1, \dots, e_m O.N.B. of $T_p M$

$$K_p(\text{span}\{e_i, e_j\}) = R_{ijij}$$

Q: Does sectional curvature determine Riem completely?

A: Yes!

Thm: The sectional curvatures determines Riem. curvature tensor.

ie. If $R^{(1)}, R^{(2)}$ are $(0,4)$ -tensors satisfying the symmetries (1) - (3) of Riem.

then $R^{(1)} = R^{(2)}$.

Note: This is just an algebraic statement:

knowing R_{ijij} $\xrightarrow[\text{symm.}]{\text{w.l.}}$ knowing R_{ijkl}

Proof: Let $R = R^{(1)} - R^{(2)}$, then R satisfies the symmetries (1) - (3).

sectional curvatures of $R^{(1)}, R^{(2)}$ agree. $\Rightarrow R(X, Y, X, Y) = 0 \quad \forall X, Y$ o.n. of $T_p M$.

To show $R(X, Y, Z, W) = 0 \quad \forall X, Y, Z, W$

it suffices to show the case $(X, Y), (Z, W)$ are mutually o.n.

Claim 1: $R(X, Y, Z, Y) = 0$ (ie. $Y = W$).

$$0 = R\left(\frac{X+Z}{\sqrt{2}}, Y, \frac{X+Z}{\sqrt{2}}, Y\right) = \frac{1}{2} R(X+Z, Y, X+Z, Y) = R(X, Y, Z, Y)$$

\Rightarrow case $m=3$ true.

Claim 2: $R(X, Y, Z, W) = 0$ for $m \geq 4$.

$$0 = R\left(X, \frac{Y+W}{\sqrt{2}}, Z, \frac{Y+W}{\sqrt{2}}\right) = \frac{1}{2} R(X, Y+W, Z, Y+W)$$

by Claim 1 $\rightarrow = \frac{1}{2} (R(X, Y, Z, W) + R(X, W, Z, Y))$

$$\Rightarrow R(X, Y, Z, W) = -R(X, W, Z, Y) = R(X, W, Y, Z)$$

$$= -R(X, Z, Y, W) = R(X, Z, W, Y) = 0$$

\leftarrow by 1st Bianchi identity.

Cor: g has constant sectional curvature $\equiv K_0 \in \mathbb{R}$ everywhere.

$$\Rightarrow R_{ijkl} = K_0 (g_{ik} g_{jl} - g_{il} g_{jk})$$

Next: Riem is a (0,4)-tensor which admits a natural algebraic decomposition into 3 parts:

$$\text{Riem} = \text{"W"} + \text{"Ric"} + \text{"R"}$$

\uparrow
Weyl curvature

\uparrow
trace-free Ricci curv

\uparrow
scalar curvature

By take traces of the (0,4) - tensor $Riem = R_{ijkl}$:

Defⁿ : $Ric(x, Y) := \sum_{i=1}^m R(x, e_i, Y, e_i)$ ← Ricci curvature
 where e_1, \dots, e_m o.n.B. for $T_p M$

$Scal = R := \sum_{i=1}^m Ric(e_i, e_i)$ ← Scalar curvature

Observations: • Ric is a (0,2) - tensor, R is a function.

• locally: $Ric = R_{jl} = R^i_{jil}$ (= ^{o.n.B.} $R_{ijil} = R_{jile_i}$)

$R = R^j_j = R^{ij}_{ij}$ (= ^{o.n.B.} R_{ijij})

• $Ric(x, Y) = Ric(Y, x) \Rightarrow Ric$ is a symm (0,2) - tensor (like g)

• m=2 : $R = 2K$.

• $Ric(x, x) := \sum_{i=1}^m R(x, e_i, x, e_i) = \sum_{j=2}^m \underbrace{R(e_i, e_j, e_i, e_j)}_{\text{sect. curv of span}\{e_i, e_j\}}$
 say $x = e_1, e_2, \dots, e_m$ o.n.B.



So, $Ric(x, x) \approx$ average sectional curv. of $\pi \ni x$.

Recall: For any symm. (0,2) - tensor h. we have a decomposition

$$h = \underbrace{\overset{\circ}{h}}_{\text{trace-free part}} + \underbrace{\frac{Tr(h)}{m} g}_{\text{trace part}}$$

Think in terms of matrix:

$$A = \overset{\circ}{A} + \frac{Tr(A)}{m} I$$

$$\begin{pmatrix} 1 & 2 \\ 2 & 2 \end{pmatrix} = \begin{pmatrix} -1/2 & 2 \\ 2 & 1/2 \end{pmatrix} + \begin{pmatrix} 3/2 & 0 \\ 0 & 3/2 \end{pmatrix}$$

$tr A = 3$ $tr \overset{\circ}{A} = 0$ $tr = 3$

Defⁿ: (Kulkarni-Nomizu Product ◦)

$$(h \circ P)_{ijk\ell} := h_{ik} P_{j\ell} + h_{j\ell} P_{ik} - h_{j\ell} P_{i\ell} - h_{i\ell} P_{jk}$$

↑ ↑
⏟

symm. (0,2)-tensors
same symmetries as $R_{ijk\ell}$

Then.

$$\text{Riem} = W + \frac{1}{m-2} \overset{\circ}{\text{Ric}} \cdot g + \frac{R}{2m(m-1)} g \cdot g$$

← scalar curvature

- Remarks:
- $W_{ijk\ell}$ is "trace-free" (i.e. $W_{ijj\ell} = 0$)
 - $\overset{\circ}{\text{Ric}} := \text{Ric} - \frac{R}{m} g$ is the trace-free Ricci tensor

Prop: (Weyl curvature tensor)

(i) $m=2$; then $W \equiv 0$, $\overset{\circ}{\text{Ric}} \equiv 0$, and $R = 2K$.

(ii) $m=3$: $W \equiv 0$ (i.e. Riem is determined by $\overset{\circ}{\text{Ric}}$)

(iii) W is "conformally invariant", i.e.

$$\tilde{g} = e^{2u} g \quad \Rightarrow \quad \tilde{W} = e^{2u} W$$

for some $u \in C^\infty(M)$

Proof: HW problems.

Remark: When $m \geq 4$, $W_g \equiv 0 \iff g$ is "locally conformally flat"
 (i.e. \exists coord system s.t. $g_{ij} = e^{2u} \delta_{ij}$)